GP2Y3A003K0F
Optoelectronic Device

FEATURES
• Trigger point set at factory to 25°
• Analog output
• Effective Range: 40 to 300 cm
• Typical response time: 16.5 ms
• Typical start up delay: 21.5 ms

DESCRIPTION
The GP2Y3A003K0F is a distance measuring sensor with integrated signal processing and analog voltage output.

Figure 1. Pinout

Figure 2. Block Diagram
ELECTRICAL SPECIFICATIONS

Absolute Maximum Ratings

Ta = 25°C, V_{CC} = 5 VDC

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>RATING</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Supply Voltage</td>
<td>V_{CC}</td>
<td>-0.3 to +7.0</td>
<td>V</td>
</tr>
<tr>
<td>Output Terminal Voltage</td>
<td>V_{O}</td>
<td>-0.3 to (V_{CC} + 0.3)</td>
<td>V</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>V_{IN H/L LED H/L}</td>
<td>-0.3 to (V_{CC} + 0.3)</td>
<td>V</td>
</tr>
<tr>
<td>Operating Temperature</td>
<td>T_{opr}</td>
<td>-10 to +60</td>
<td>°C</td>
</tr>
<tr>
<td>Storage Temperature</td>
<td>T_{stg}</td>
<td>-40 to +70</td>
<td>°C</td>
</tr>
</tbody>
</table>

Operating Supply Voltage

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>RATING</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Operating Supply Voltage</td>
<td>V_{CC}</td>
<td>4.5 to 5.5</td>
<td>V</td>
</tr>
</tbody>
</table>

Electro-optical Characteristics

DISTANCE MEASURING SENSOR

Ta = 25°C, V_{CC} = 5 VDC

<table>
<thead>
<tr>
<th>PARAMETER</th>
<th>SYMBOL</th>
<th>CONDITIONS</th>
<th>MIN.</th>
<th>TYP.</th>
<th>MAX.</th>
<th>UNIT</th>
</tr>
</thead>
<tbody>
<tr>
<td>Measuring Distance Range</td>
<td>\delta L</td>
<td></td>
<td>40</td>
<td>—</td>
<td>300</td>
<td>cm</td>
</tr>
<tr>
<td>Output Terminal Voltage</td>
<td>V_{O}</td>
<td>L = 40 cm</td>
<td>2.0</td>
<td>2.3</td>
<td>2.6</td>
<td>V</td>
</tr>
<tr>
<td>Output Voltage Gap</td>
<td>\delta V_{O}</td>
<td>Output voltage gap between L = 40 cm and L = 100 cm</td>
<td>0.9</td>
<td>1.2</td>
<td>1.5</td>
<td>V</td>
</tr>
<tr>
<td>Average Supply Current</td>
<td>I_{CC}</td>
<td></td>
<td>—</td>
<td>30</td>
<td>50</td>
<td>mA</td>
</tr>
<tr>
<td>Input Voltage</td>
<td>V_{IN H}</td>
<td>Input voltage for operating distance measuring sensor</td>
<td>4.5</td>
<td>—</td>
<td>—</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td>V_{IN L}</td>
<td>Input voltage for turning off distance measuring sensor</td>
<td>—</td>
<td>—</td>
<td>0.3</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td>LED H</td>
<td>Input voltage for turning LED ON</td>
<td>4.5</td>
<td>—</td>
<td>—</td>
<td>V</td>
</tr>
<tr>
<td></td>
<td>LED L</td>
<td>Input voltage for turning LED OFF</td>
<td>—</td>
<td>—</td>
<td>0.5</td>
<td>V</td>
</tr>
</tbody>
</table>

NOTES:
1. Measurements made with Kodak R-27 Gray Card, using the white side, (90% reflectivity).
2. L = Distance to reflective object.
**NOTE:** Output voltage is unstable without $V_{\text{IN}}$ H.

**Figure 3. Timing Diagram**
REALIABILITY

The reliability requirements of this device are listed in Table 1.

Table 1. Reliability

<table>
<thead>
<tr>
<th>TEST ITEMS</th>
<th>TEST CONDITIONS</th>
<th>FAILURE JUDGEMENT CRITERIA</th>
<th>SAMPLES (n), DEFECTIVE (C)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Temperature Cycling</td>
<td>One cycle -40°C (30 min.) to +70°C in 30 minutes, repeated 25 times</td>
<td></td>
<td>n = 11, C = 0</td>
</tr>
<tr>
<td>High Temperature and High Humidity Storage</td>
<td>+40°C, 90% RH, 500h</td>
<td></td>
<td>n = 11, C = 0</td>
</tr>
<tr>
<td>High Temperature Storage</td>
<td>+70°C, 500h</td>
<td></td>
<td>n = 11, C = 0</td>
</tr>
<tr>
<td>Low Temperature Storage</td>
<td>-40°C, 500h</td>
<td></td>
<td>n = 11, C = 0</td>
</tr>
<tr>
<td>Operational Life (High Temperature)</td>
<td>+60°C, V_{CC} = 5 V, 500h</td>
<td>Initial × 0.8 &gt; V_{O}</td>
<td>n = 11, C = 0</td>
</tr>
<tr>
<td>Mechanical Shock</td>
<td>100 m/s², 6.0 ms 3 times/±X, ±Y, ±Z direction</td>
<td></td>
<td>n = 8, C = 0</td>
</tr>
<tr>
<td>Variable Frequency Vibration</td>
<td>10-to-55-to-10 Hz in 1 minute Amplitude: 1.5 mm 2h in each X, Y, Z direction</td>
<td></td>
<td>n = 8, C = 0</td>
</tr>
</tbody>
</table>

NOTES:
1. Test conditions are according to Electro-optical Characteristics, shown on page 2.
2. At completion of the test, allow device to remain at nominal room temperature and humidity (non-condensing) for two hours.
3. Confidence level: 90%, Lot Tolerance Percent Defect (LTPD): 20%/40%.

MANUFACTURER’S INSPECTION

Inspection Lot

Inspection shall be carried out per each delivery lot.

Inspection Method

A single sampling plan, normal inspection level II based on ISO 2859 shall be adopted.

Table 2. Quality Level

<table>
<thead>
<tr>
<th>DEFECT</th>
<th>INSPECTION ITEM and TEST METHOD</th>
<th>AQL (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Major Defect</td>
<td>Electro-optical characteristics defect</td>
<td>0.4</td>
</tr>
<tr>
<td>Minor Defect</td>
<td>Defect to appearance or dimensions (crack, split, chip, scratch, stain)*</td>
<td>1.0</td>
</tr>
</tbody>
</table>

NOTE: *Any one of these that affects the Electro-optical Characteristics shall be considered a defect.
Figure 4. GP2Y0D21YK Example of Output Distance Characteristics
PACKAGE SPECIFICATIONS

NOTES:
1. Unspecified tolerances are ±0.3 mm.
2. The connector is made by Molex, part number is 53047-0910.
3. (): Reference value.
4. Dimensions are in mm.

CONNECTOR SIGNAL

<table>
<thead>
<tr>
<th>PIN</th>
<th>SIGNAL NAME</th>
</tr>
</thead>
<tbody>
<tr>
<td>1 - 5</td>
<td>Signal inputs for selecting LED 1 - 5</td>
</tr>
<tr>
<td>6</td>
<td>( V_O )</td>
</tr>
<tr>
<td>7</td>
<td>GND</td>
</tr>
<tr>
<td>8</td>
<td>( V_{CC} )</td>
</tr>
<tr>
<td>9</td>
<td>( V_{IN} ) Control input for distance measuring operation</td>
</tr>
</tbody>
</table>

STAMP EXAMPLE

- Model Name: 2Y3A003 F
- Month (1 to 9, X, Y, Z)
PACKING SPECIFICATION

PACKING METHOD
1. Each tray holds 50 pieces. Packing methods are shown in (A).
2. Each box holds 10 trays. Pads are added to top and bottom, and between layers, as in (B). Top and bottom. Put pads between each tray (9 pads total) see above drawing (B).
3. The box is sealed with craft tape. (C) shows the location of the Model number, Quantity, and Inspection date.
4. Package weight: Approximately 4 kg.

<table>
<thead>
<tr>
<th>PART NAME</th>
<th>MATERIAL</th>
</tr>
</thead>
<tbody>
<tr>
<td>Packing case</td>
<td>Corrugated cardboard</td>
</tr>
<tr>
<td>Pad</td>
<td>Corrugated cardboard</td>
</tr>
<tr>
<td>Tray</td>
<td>Polystyrene</td>
</tr>
</tbody>
</table>

GP2Y3A003K0F-9
NOTES

- Keep the sensor lens clean. Dust, water, oil, and other contaminants can deteriorate the characteristics of this device. Applications should be designed to eliminate sources of lens contamination.
- When using a protective cover over the emitter and detector, ensure the cover efficiently transmits light throughout the wavelength range of the LED ($\lambda = 850 \text{ nm} \pm 70 \text{ nm}$). Both sides of the protective cover should be highly polished. Use of a protective cover may decrease the effective distance over which the sensor operates. Ensure that any cover does not negatively affect the operation over the intended application range.
- Objects in proximity to the sensor may cause reflections that can affect the operation of the sensor.
- Sources of high ambient light (the sun or strong artificial light) may affect measurement. For best results, the application should be designed to prevent interference from direct sunlight or artificial light.
- Using the sensor with a mirror can induce measurement errors. Often, changing the incident angle on the mirror can correct this problem.
- If a prominent boundary line exists in the surface being measured, it should be aligned vertically to avoid measurement error. See Figure 5 for further details.
- When measuring the distance to objects in motion, align the sensor so that the motion is in the horizontal direction instead of vertical. Figure 6 illustrates the preferred alignment.
- A 10 µF (or larger) bypass capacitor between $V_{CC}$ and GND near the sensor is recommended.
- To clean the sensor, use a dry cloth. Use of any liquid to clean the device may result in decreased sensitivity or complete failure.
- Excessive mechanical stress can damage the internal sensor or lens.

![Figure 5. Proper Alignment to Surface Being Measured](GP2Y3A003K0F-1)

![Figure 6. Proper Alignment to Moving Surfaces](GP2Y3A003K0F-2)
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Countries and Areas

U.S.A.

SHARP MICROELECTRONICS OF THE AMERICAS
North American Head Office
5700 North West Pacific Rim Boulevard
Camas, Washington 98607 USA
PHONE: (1)360-834-2500
FAX: (1)360-834-8903
http://www.sharpsma.com

Western Area
1960 Zanker Road, San Jose, CA 95112
PHONE: (1)408-436-4900
FAX: (1)408-436-0924
5901 Bolsa Ave.
Huntington Beach, CA 92647-2053
PHONE: (1)714-903-4600
FAX: (1)714-903-0295
6390 Greenwich Drive, Suite 175
San Diego, CA 92122
PHONE: (1)858-597-0982
FAX: (1)858-597-8701

Central Area
85 W. Algonquin Road, Suite 280
Arlington Heights, IL 60005
PHONE: (1)847-228-2700
FAX: (1)847-439-2479
6303 Commerce Drive, Suite 175
Irving, TX 75063
PHONE: (1)972-582-1710
FAX: (1)972-580-7537
8911 Capitol of Texas Hwy, Suite 3130
Austin, TX 78759
PHONE: (1)512-349-7262
FAX: (1)512-349-7002
20333 State Hwy. 249, Suite 200
Houston, TX 77070
PHONE: (1)281-378-1520
FAX: (1)281-378-1521
W129 S 9647 Tony Lena Muskego, WI 53150
PHONE: (1)414-529-9568
FAX: (1)414-529-9569
3001 West Big Beaver Road, Suite 722
Troy, MI 48064
PHONE: (1)248-458-1527
FAX: (1)248-458-6255

Eastern Area
1070 N. Kimbles Road, Yardley, PA 19067
PHONE: (1)215-321-5530
FAX: (1)215-321-5534
200 Wheeler Rd., Burlington, MA 01803
PHONE: (1)781-270-7979; (1)781-229-5100
FAX: (1)781-229-9117
8000 Regency Parkway, Suite 280 Cary, NC 27511
PHONE: (1)919-460-0695
FAX: (1)919-460-0795
2321 Sidney St. Pittsburgh, PA 15203
PHONE: (1)412-381-1191
FAX: (1)412-381-1192
4875 North Federal Highway, Third Floor
Ft. Lauderdale, FL 33318
PHONE: (1)954-267-8883
FAX: (1)954-267-8254

EUROPE

SHARP MICROELECTRONICS EUROPE
A division of Sharp Electronics (Europe) GmbH
Head Office
Sonninstrasse 3, 20097, Hamburg, Germany
PHONE: (49)180-5073507
FAX: (49)49-2376-2232
http://www.sharpsme.com/

Germany
SME München Office
Fuerstenriederstrasse 5, 80687 München, Germany
PHONE: (49)89-5468420
FAX: (49)89-54 684280

France
SME Paris Office
1 Rue Raoul Follereau Bussy Saint Georges
78708 Mame la Vallee Cedex 3
PHONE: (33)1 6476 22 23
FAX: (33)1 6476 22 23

Italy
SME Milano Office
Centro Direzionale Colleoni
Palazzo Taurus Ingresso 2
20041 Agridate Bria, Milano, Italy
PHONE: (39)39-58 99 94 96
FAX: (39)39-68 99 94 94

U.K.
SME London Office
Centenial Court, Easthampstead Road,
Bracknell, Berkshire RG1 1YQ, United Kingdom
PHONE: (44)1344-86 99 22
FAX: (44)1344-36 09 03

Ireland
SME Dublin Office
First Floor, Block 1, St. Johns Court, Santry,
Dublin 9, Ireland
PHONE: (353)1-842 87 05
FAX: (353)1-842 84 55

ASIA

SHARP ELECTRONICS (SHANGHAI) CO., LTD.
Microelectronics Sales & Marketing Division
16F, King Tower, 28 Xin Jin Qiao Road,
Pudong DiST, Shanghai 201206 P.R. China
PHONE: (86)21-5854-7710/21-5834-6056
FAX: (86)21-5854-4340/21-5834-6057

 Distributed By

Registered Address
No.11, De Bao Road, Xin Development BLDG
46 Wai Gao Qiao Free Trade Zone, Shanghai
200131, P.R. China

Beijing Office
Room 1062, Beijing Jing An Center No. 8 East
Bei San Huan Road, Chao Yang DIST, Beijing
100028 P.R. China
PHONE: (86) 10-6466-7543/10-6466-6561
FAX: (86) 10-6468-8920

SHARP-ROXY (HONG KONG) LTD.
Device Sales Division, 17/F, Admiralty Centre,
Tower 1, 18 Harcourt Road, Hong Kong
PHONE: (852)28229911
FAX: (852)28600779
http://www.sharp.com.hk

Shenzhen Representative Office
Room 13B1, Tower C, Electronics Science & Technology Building, Shen Nan Zhong Road, Shenzhen, P.R. China
PHONE: (86)755-83273731
FAX: (86)755-83273735

SHARP ELECTRONIC COMPONENTS (TAIWAN) CORPORATION
8F-A, No. 16, Sec. 4, Nanking E. Rd., Taipei, Taiwan
PHONE: (886)2-2577-7341
FAX: (886)2-2577-7326/2-2577-7328

SHARP ELECTRONICS (SINGAPORE) PTE., LTD.
396 Alexandra Road #07-00
BP Tower Singapore 119954
PHONE: (65) 62713668
FAX: (65) 62713855
http://www.sesl-sharp.com

SHARP MICROELECTRONICS TECHNOLOGY (M) SDN BHD.
Suite E 408, 4th Floor, East Tower,
Wisma Conplant 1, No. 2 Jln. SS 16/4,
Subang Jaya, 47500, Selangor Darul Ehsan, Malaysia
PHONE: (60) 3-5637-8964
FAX: (60) 3-5638-4029

SHARP ELECTRONIC COMPONENTS (KOREA) CORPORATION
RM 501 Ilsin B.D. 541, Dohwa-dong, Mapo-ku, Seoul, Korea, 121-701
PHONE: (82)2-711-5813 – 8
FAX: (82)2-711-5819

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